(54) Title: LOUDSPEAKERS

(57) Abstract: A loudspeaker comprising a panel-form acoustic member intended for operation as a bending wave radiator and an electrodynamic moving coil transducer having a voice coil mounted to the acoustic member to excite bending wave vibration in the acoustic member, wherein the junction between the voice coil and the acoustic member is of sufficient length in relation to the size of the acoustic member to represent a line drive such that the acoustic member has a mechanical impedance which has a rising trend with bending wave frequency.

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5   TITLE: LOUDSPEAKERS

10   DESCRIPTION

15   TECHNICAL FIELD

The invention relates to bending wave panel loudspeakers, e.g. resonant bending wave panel speakers of the kind exemplified by WO97/09842, and to drive motors for such speakers.

20   BACKGROUND ART

In making electro-dynamic, that is moving coil, vibration transducers for bending wave panel speakers, current thinking on voice coil size and mass tends towards the use of small diameter and low mass voice coil systems, 25 typically of the size of tweeter coils of conventional pistonic speakers. In certain applications, e.g. for driving bending wave panels or diaphragms as exemplified by WO98/39947, which are intended to be driven centrally

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e.g. so that they can act both pistonically and in bending, such small diameter voice coils may cause power handling and excursion-related problems.

For such small diameter voice coils the drive point
5 impedance (Zm) approximates to that of a panel driven at a single point. As the frequency is increased Zm oscillates with modal structure but is on average constant and approximates to the infinite panel value given by the following equation:

$$Zm = 8\sqrt{B\mu}$$

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As a result for a given voice coil mass (Mc) there is a high frequency limit (f(b)) above which the rising impedance of this mass exceeds the constant drive point impedance. This frequency is given by the following
15 equation:

$$f(b) = \frac{Zm}{2\pi Mc}$$

Consequently the voice coil mass on known bending wave panels has been kept low according to the above formula.

20   The obvious way is to increase Zm or reduce Mc in order to keep the turnover frequency high in the audio band. Voice coil diameter has only ever been increased slightly and then only to find that the cell cap, drum-mode, resonance becomes dominant and causes premature
25 roll-off.

Other issues that work against low mass voice coils for pistonically driven panels are sensitivity and bandwidth. In order to keep a realistic low frequency bandwidth in a realistic enclosed volume, the diaphragm

5 mass needs to be high. So to keep sensitivity up, the Bl force factor will need to be high. High Bl drivers usually rely on the number of turns to increase the Bl product and thus increase voice coil mass.

Another direction is to use an under-hung vibration

10 exciter design relying on the magnet to increase the Bl product and thus keeping voice coil mass low. This has been trialled using a 25mm voice coil diameter and an increased stiffness over the drive point. But power handling and excursion are still restricted.

15   It is known from WO97/09842 to provide a flat panel loudspeaker which operates pistonically at low frequencies and which is resonant at high frequencies. It is also known from US-A-4,542,383 to provide a loudspeaker having a moving coil transducer and a diaphragm, both being of

20 similar diameter and the voice coil being arranged to drive the diaphragm around its periphery.

                    DISCLOSURE OF INVENTION

        According to the invention, there is provided a loudspeaker comprising a panel-form acoustic member

25 intended for operation as a bending wave radiator and an electrodynamic moving coil transducer having a voice coil mounted to the acoustic member to excite bending wave vibration in the acoustic member, wherein the junction

between the voice coil and the acoustic member is of sufficient length in relation to the size of the acoustic member to represent a line drive such that the acoustic member has a mechanical impedance which on average rises

5 with bending wave frequency. The junction of the voice coil and the diaphragm may be circular and the junction may be substantially continuous.

A sufficient length voice coil junction in the present context, is one in which the length, or its

10 diameter in the case of a circular junction, is equal to at least the length of a bending wave in the portion of the acoustic member defined by the junction, or circumscribed by the voice coil, at the highest operating frequency of the loudspeaker.

15 The mechanical impedance of a panel is equal to the ratio of force applied at a single point to the resultant velocity at this point. Where the panel is driven by force acting over a line, the effective mechanical impedance is the ratio of total force applied over the

20 line to the resultant velocity averaged over the length of the line. In the present description and claims the use of the term mechanical impedance is used to describe this ratio for both drive arrangements.

It will be understood that for a point driven plate

25 or diaphragm it is only an infinite diaphragm that has a truly constant Zm. A finite diaphragm has a Zm that oscillates about the infinite diaphragm value. Similarly the mechanical impedance seen by a large area voice coil

on the diaphragm will oscillate with modal structure but will on average rise with frequency.

The portion of the acoustic member circumscribed by the said voice coil may be of different stiffness to a

5 portion of the acoustic member outside the voice coil.

The transducer may be arranged both to move the acoustic member in whole body mode and to apply bending wave energy to the acoustic member. The size, shape and position of the junction between the voice coil and the

10 acoustic member may be adjusted in relation to the modal distribution of the diaphragm or acoustic member in order to achieve a smooth transition from whole body motion at low frequencies to resonant bending wave behaviour at higher frequencies. By way of example, in

15 the case of a circular diaphragm, normally driven, the second resonance may give rise to an irregularity in the output. With a circular driveline the effective perimeter of the driveline may be chosen in location and size to lie on or near to the nodal circle of the second

20 resonance. In this context the first resonance is the whole body or piston equivalent resonance. By coupling at or near the nodal circle for the second resonance its effect is reduced and the mode is driven weakly or not at all. Thus the designer may adjust the drive

25 parameters to increase the sound quality from the low piston frequencies to the modally denser region at mid frequencies.

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Mass loading may be applied to the acoustic member within the diameter of the voice coil. The acoustic member may be non-circular in shape. The transducer voice coil may be concentric with the geometric centre of the 5 acoustic member.

A second transducer may be coupled to the acoustic member within the portion thereof circumscribed by the said voice coil and adapted to cause high frequency bending wave activity of the said portion. The second 10 transducer may be offset from the axis of the said voice coil.

Coupling means may be provided to attach the said voice coil to the acoustic member, the coupling means having a footprint of non-circular shape.

15   The portion of the acoustic member circumscribed by the voice coil may be stiffer than a portion of the acoustic member outside the voice coil. The bending stiffness of the acoustic member may be anisotropic. The acoustic member may be curved or dished or otherwise 20 formed to increase its bending stiffness.

The loudspeaker may comprise a chassis having a portion surrounding the acoustic member, and a further portion supporting the electrodynamic transducer, and may further comprise means connected between the acoustic 25 member and the said chassis portion and resiliently suspending the acoustic member on the chassis. The

suspension means may be connected between the chassis and the margin of the acoustic member. The resilient suspension may be adapted to mass load the acoustic member. The resilient suspension may be adapted to damp

5 the acoustic member. The resilient suspension may be at least partly formed by a skin of the acoustic radiator.

The acoustic member may have a front side from which acoustic energy is radiated, and may comprise acoustic masking means positioned over the portion of the acoustic

10 member circumscribed by the said voice coil, the masking means defining an acoustic aperture.

The electrodynamic moving coil transducer may be offset from the geometric centre of the acoustic member, and a counter balance mass may be provided on the acoustic

15 member.

The action of the large area voice coil on the diaphragm can produce a distribution of excited modes that results in significant beaming of the radiation on-axis, at least over some of the frequency range. In some

20 applications, such as zoning of the output sound, this may be advantageous, but in many applications off-axis power is desirable. One approach to improving off-axis power is to excite the panel in bending wave vibrations at frequencies near to or greater than the coincidence

25 frequency.

The coincidence frequency is the frequency at which the bending wave velocity in the plate equals the velocity of sound in air. Above this frequency the velocity in the plate exceeds the velocity in air, and this supersonic vibration can give rise to strongly directional radiation off-axis. In fact at the coincidence frequency, radiation is beamed directly off-axis, with the angle of beaming moving closer to the on-axis direction with increasing frequency. The coincidence frequency of a plate is determined by its bending stiffness (B) and mass density (mu). These parameters may be varied such that the narrowing of the radiation pattern resulting from the large area voice coil is compensated for, at least to some degree, by the additional energy beamed off-axis by the bending wave vibration above the coincidence frequency.

The loudspeaker of the present invention may be adapted to operate as a full range device.

BRIEF DESCRIPTION OF DRAWINGS

The invention is diagrammatically illustrated, by way of example, in the accompanying drawings, in which:-

Figure 1 is a front view of a loudspeaker driver motor;

Figure 2 is a cross-sectional side view of the drive motor of Figure 1;

Figure 3 is a front view of a loudspeaker enclosure;

Figure 4 is a side view of the loudspeaker enclosure;

Figure 5 is a graph of frequency response;

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Figure 6 is a graph of near field bass frequency response;

Figures 7 to 9 are front views of embodiments of diaphragm each having a supplementary vibration exciter;

5   Figures 10 to 13 are front views of further embodiments of diaphragm;

Figure 14 is a perspective diagram of a further embodiment of diaphragm;

Figures 15 to 18 cross-sectional views of embodiments 10 of diaphragm;

Figures 19 to 21 show cross-sections of embodiments of diaphragm surrounds or suspensions;

Figure 22 is a cross-sectional view of an embodiment of speaker driver motor;

15   Figure 23 is front view of an embodiment of diaphragm;

Figure 24 is a cross-sectional view of an embodiment of diaphragm;

Figure 25 is a polar diagram comparing the response 20 of a conventional pistonic speaker with that of the present invention, and

Figures 26 and 27 are front views of further embodiments of voice coil/diaphragm line drive junctions.

BEST MODES FOR CARRYING OUT THE INVENTION

25   In Figures 1 and 2 there is shown a loudspeaker driver motor (1) adapted to be mounted to a baffle, e.g. in an enclosure, see Figures 3 and 4 below, comprising a circular flat diaphragm of stiff lightweight material,

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comprising, for example, a core sandwiched between skins of high tensile sheet material, which forms an acoustic member or radiator intended to operate both pistonically and by flexure as a bending wave resonant device at higher

5 frequencies. In this way the driver motor of the present invention is able to operate as a full range device covering substantially the whole of the audio spectrum with wide acoustic dispersion, unlike a conventional pistonic driver, whose frequency band or at least its

10 dispersion angle is limited at high frequencies by the diameter of the diaphragm, see Figure 25 below, and a bending wave driver, which tends to roll-off at frequencies below about 200Hz, unless of very large diaphragm size.

15   In generally conventional manner the diaphragm (2) is supported in a chassis or basket (3), e.g. of metal formed at its front with an annular flange (4) having a plurality of spaced fixing holes (5) whereby the chassis can be fixed in a suitable aperture a loudspeaker enclosure, see

20 Figures 3 and 4 below. A corrugated suspension (6) e.g. of rubber-like material is fixed to the diaphragm round its periphery by means of an adhesive and the suspension is clamped to the annular flange (4) with the aid of a clamping ring (7), whereby the diaphragm can move

25 pistonically relative to the chassis.

        The chassis supports an electrodynamic moving coil transducer (8) for moving the diaphragm pistonically and for applying bending wave energy to the diaphragm to cause

it to resonate, e.g. in the manner generally described in WO97/09842. The transducer comprises a magnet assembly (9) fixed to the chassis and defining an annular gap (10) concentric with the diaphragm and a voice coil and former

5   assembly (11) mounted for axial movement in the annular gap and which is fixed to the diaphragm concentrically therewith by a coupler ring (12). In generally conventional fashion, a corrugated suspension spider (13) is fixed between the voice coil assembly and the chassis

10 to ensure the proper axial movement of the voice coil in the annular gap.

The voice coil diameter is large in relation to the bending wave length and the effect of this is that of a line drive to the diaphragm instead of a point drive as is

15 normal for bending wave radiators using electrodynamic exciters having small diameter voice coils. This line drive provides a significant increase in the mechanical drive impedance presented to the voice coil, and this higher mechanical impedance enables the system to tolerate

20 relatively high mass voice coils without premature roll off of high frequencies. Also, because of the large diameter of the voice coil, it is possible to manipulate the diaphragm panel stiffness to allow the portion of the diaphragm circumscribed by the voice coil to have multiple

25 modes instead of a single dominant drum mode as can happen with a small diameter voice coil. An inner portion (16) of the diaphragm is circumscribed by the voice coil as

seen in Figure 1, while an outer portion (17) of the diaphragm extends radially outside the voice coil.

As shown in Figures 1 and 2, small masses (14,15) are attached to the diaphragm inside the voice coil diameter

5 to tune and/or smooth the frequency response of the acoustic radiator. Such masses are not always essential but may usually be desirable. These masses are shown as discrete masses but need not necessarily be discrete. They may have masses in the range 0.5 g to 100 g, and

10 typically in the range 2 to 20 g. One or more such mass may be provided.

The loudspeaker driver embodiment of Figures 1 and 2 has been optimised for use in a hi-fi loudspeaker, when coupled to an amplifier which has a flat voltage transfer

15 function throughout the audio band. With this as part of the design criteria for this embodiment, the following design parameters are applicable.

The transducer has a large 75mm diameter voice coil mounted in a low inductance motor system having a vent

20 (18), having a copper eddy current shield (19) over the pole piece or front plate (20). Figure 2 shows a cross section of a magnetic ring (21) of neodymium, centrally mounted in a steel magnetic circuit comprising a magnet cup (22) and the front plate (20) resulting in an average

25 B field of 0.8T. The voice coil (11) over-hangs the magnet front plate (20) to give an over-hung configuration. The voice coil consists of a winding height of 14.5mm of

aluminium turns on a 0.1mm thick aluminium former. The voice coil parameters are given below:

Mandrel or former diameter =75mm

Number of coil layers =2

5   Wire diameter =0.3mm

Number of turns =71

The coupler ring (12) is required to provide a secure interface between the voice coil and the diaphragm. This nests inside of the voice coil. A 2.5mm overlap is 10 provided to allow for a good bond area between the coupler and the voice coil former. The coupler ring extends the effective length of the voice coil by 1.7mm, giving a ring width of 3.5mm to couple to the diaphragm. This is show in Figure 2. The material of the coupler ring is commercial 15 grade thermoplastic or thermoset resin e.g. ABS which gives a mass of 3.4g. For the bonding between the voice coil and coupler a thermal resistant cyanoacrylate is used (Loctite 4212). This is also used to bond the coupler to the diaphragm.

20   The dynamic parameters of the motor system with the coupler ring are shown below:

Mms =11g (Moving mass of the voice coil assembly)

Rms =1.95Ns/m (Mechanical resistance of suspension)

Bl =8.1Tm (Motor conversion factor)

Re =6.5ohm (DC resistance of voice coil)

Fs =40Hz (Mass spring resonance of system)

Le =0.2mH (Inductance factor of voice coil @1kHz)

5   The diaphragm material used along with its parameters
are given below:

Material = Rotrex Lite 51LS (Trade Name) 3.5mm (3.5mm
thick 51LS grade uncompressed Rohacell (Trade Name) core of
rigid closed cell polymethacrylimide thermoplastic foam
10 with a glass veil/thermoplastic skin). Diameter =120mm.

Parameters are given below in Table 1:

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           Table 1

Mass Area Density	M	0.35	Kg/m2
Poisson ratio	N	0.11	
Bending rigidity	D1	2.4	Nm
Bending Rigidity	D2	1.8	Nm
Damping D	D	0.02	
In plane shear ratio	Shr	0.36	
Thickness	T	3.5mm	M
Shear modulus	Gz	19M	Pa
Damping Gz	D	1	
Coincidence Frequency	Fc	7.7	KHz

From the parameters given in table 1, the wavelength of the panel may be calculated at the highest frequency of operation, i.e. 20kHz. This calculation gives a
5 wavelength of 28mm, based on an average bending stiffness of 2.1 Nm. The voice coil diameter is therefore 2.7 times the wavelength at the highest frequency of operation. In the prior art of bending wave speakers, the first aperture resonance corresponds to a half wavelength within the
10 voice coil.

The coincidence lobe of this panel gives strong acoustic output off axis close to or above coincidence frequency as given in Table 1 above. As indicated in the directivity plot of Figure 25, in which the thin line or
15 trace (45) is a plot of a speaker according to the invention with a 300 mm diameter diaphragm, and the thick

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trace (44) is of a conventional pistonic diaphragm of 250 mm diameter.

The chassis consists of an aluminium back plate (23) to support the transducer (8) and which is connected to 5 the front flange (4). Allen bolts (not shown) are used to secure the clamping ring (7) to the flange (4).

The pair of masses (14,15) fixed to the diaphragm are to smooth the first drum mode within the inner portion of the diaphragm, at approximately 2kHz.

10   The motor drive unit parameters are given below:

dD=14cm (Diameter of radiating area (centre to centre of the surround))

Mms =27g (Moving mass of the voice coil and diaphragm assembly)

15   Rms =2.4Ns/m (Mechanical resistance of suspension)

Bl =8.1Tm (Motor conversion factor)

Re =6.5ohm (DC resistance of voice coil)

Fs =33Hz (Mass spring resonance of system)

Le =0.2mH (Inductance factor of voice coil @1kHz)

20   Figures 3 and 4 show a loudspeaker enclosure (24) for the drive unit of Figures 1 and 2 and having a sloping front (25) and sides (26). An aperture (27) is provided in

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the front (25) to receive the drive unit or motor (1).

The enclosure has been designed to give a volume of 17

litres giving a maximally flat alignment. The enclosure

form is chosen to smear internal enclosure standing waves,

5   although this is not essential to the design and operation

of the speaker.   The enclosure is constructed from 18mm

medium density fibreboard (MDF). The joints are glued

(using PVA wood glue) and screwed to give an air tight

seal.

10   The following measurements of the above embodiment

of the speaker were taken in an anechoic chamber with

the microphone positioned at 1m (on axis with the

diaphragm) at 2.83v.   Inaccuracies occur below

approximately 200Hz for the measurement shown in Figure

15 5, so a near field measurement showing the low frequency

performance is given in Figure 6.

While the embodiment of Figures 1 and 2 employs a

single large diameter voice coil driver, a supplementary

exciting device could be used to improve the high

20 frequency level and/or extension and directivity

performance of the loudspeaker. The supplementary exciter

could be placed anywhere on the diaphragm to provide a

smaller radiation area. Devices such as piezos of large

area, small area or strip-like form or smaller moving coil

25 devices could be used. This is illustrated in Figures 7 to

9. In Figure 7 it will be seen that a circular piezo disc

vibration exciter (28) has been mounted on the diaphragm

(2) at its centre and inside the diameter of the voice coil (11). In the embodiment of Figure 8, a piezo strip vibration exciter (29) has been mounted on the diaphragm (2) concentrically therewith and inside the diameter of

5   the voice coil (11). In Figure 9, a circular disc vibration exciter (30) has been mounted on the diaphragm (2) inside the voice coil diameter (11) but off centre.

It can be shown that the voice coil moving mass has little effect on the high frequency extension of the

10 speaker. Therefore the present invention is not restricted to lightweight voice coils. This implies scope for employing moving magnet motor systems and/or relatively high mass coupler rings between the voice coil assembly and the diaphragm which currently might be excluded from

15 small drive area or point drive designs of bending wave speaker. This could allow complex coupler designs to transform the voice coil ring to other beneficial shapes so as to improve performance. Examples of triangular, square and oval shapes of coupler ring are shown in

20 Figures 10 to 12 respectively under references (31) to (33) respectively. These shapes have implications on the distribution of modes excited and therefore directivity implications. If for example, as shown in Figure 13, a rectangular diaphragm (34) has been chosen this, together

25 with a rectangular coupler ring (32) rotated by an angle relative to the diaphragm sides, could provide a more

irregular modal pattern in the diaphragm. This could also further improve frequency response on and off axis.

In the embodiment of Figures 1 and 2, the voice coil diameter is 75mm. This can be increased or decreased depending on the design specification. If the design specification requires narrow directivity for zoning applications, a larger voice coil coupled to a low wave speed panel, i.e. having a very high Fc, could be used. Conversely, if wide directivity is required a smaller voice coil can be used, within the criteria of line drive. However this may need electrical high frequency boost to maintain constant pressure throughout the audio band.

As indicated in Figure 13 above, the invention is not limited to the circular panel shape shown in the embodiment of Figures 1 and 2. Other shapes can be beneficial in directivity and/or frequency response, because of the different mode shapes that result from the geometry of the panel. It is expected that the more complex the mode shapes in the panel, the less directivity there will be in the acoustic output. Examples include square, rectangular and hexagonal panels.

Also, as shown in Figure 14, the invention is not restricted to pure piston behaviour of the diaphragm at low frequency, and may be quasi-tympanic at low frequencies. The diaphragm (34) could be a large radiating panel. This would provide a means of self-baffling giving

a dipole bass response as indicated by opposed arrows. The panel edges could be free or clamped.

The invention is not restricted to a flat diaphragm or to a single material type. Profiling and shaping of the
5 diaphragm can be used to alter the modal behaviour. For example, the part of the diaphragm circumscribed by the voice coil could be constructed from a different material or the same material but thicker or thinner. Exemplary embodiments are shown in Figures 15 to 18. Stiffness can
10 be applied to the diaphragm by profiling. Stiffness variation can also be realised by using material isotropy. Thus in Figure 15, the inner portion (16) of the diaphragm (2) is thinned by dishing its undersurface. In Figure 16, the inner portion (16) of the diaphragm is
15 thickened. In Figure 17, the inner portion (16) of the diaphragm (2) is uniformly thinner than the outer portion (17) of the diaphragm. In Figure 18 the outer portion (17) of the diaphragm (2) progressively tapers in thickness towards the inner portion, as soon in the left-
20 hand side of the Figure, and is formed with a curved profile of varying thickness as seen on the right-hand side of the Figure.

It can be shown that the diaphragm surround affects acoustic performance. Both the piston and modal region can
25 be varied by changing the material properties of the surround. In particular, if mass is applied to the perimeter of the diaphragm as shown at (36) in Figure 19,

high frequency performance can be improved.   Edge damping
of the diaphragm can be applied to control its modal
behaviour. This can be in the form of surface treatment or
edge damping can be by means of the surround footprint, as
5 indicated at (37) in Figure 20. The panel skins, or one of
them, could be used to form the surround as indicated in
Figure 21.   In this embodiment the diaphragm comprises a
core (38) and skins (39,40) covering the core.   The lower
skin (40) is extended to form the surround or suspension
10 (6). This may give cost advantages. Advantages could also
include low-loss termination of the diaphragm.

Radiation at frequencies close to and greater than
the coincidence frequency (fc) is used in the preferred
embodiment to widen directivity at high frequency. However
15 coincidence can be set at either end of the spectrum.
Increasing the panel stiffness/lowering the coincidence
frequency should still give wide directivity and improved
modal region sensitivity.

Using isotropic diaphragms, e.g. at approximately two
20 times Fc, will give side lobes in the same position in
both planes. When using non-isotropic panels, coincidence
can be set independently in alternate planes thus giving a
smoother total power response.

Mechanical components, e.g. mass or voice coil coupling
25 to the panel, can provide a means of mechanical filtering.
By placing an interface between the voice coil coupler and

the panel the frequency response can be modified. Passive component electrical shelving or amplifier transfer function shelving/high frequency boost could also be employed to modify the acoustic output of the device.

5   In the embodiment of Figures 1 and 2, coherent sound radiates from the annular area where the voice coil is fixed to the diaphragm. This can cause beaming at high frequencies due to the large radiating area relative to the wavelength in air. As shown in Figure 22, to widen the
10 directivity at high frequencies, a mask (41) having a small aperture (42) can be placed over the inner portion (16) of the diaphragm (2) on a support (43) mounted on the chassis (3) to transform this into a smaller radiating area. This effect has been seen when measurements have
15 been taken from the rear of the device. In the embodiment of Figures 1 and 2 the vent (18) in the motor system forms the mask aperture, as concerns rear radiation.

If desired, as shown in Figure 23, the voice coil (11) may be positioned off-centre on the diaphragm (2) to
20 improve the distribution of resonant modes excited in the diaphragm, with a counterbalancing mass (35) positioned on the diaphragm to prevent rocking.

As shown in Figure 24, the diaphragm (2) need not be flat and can be dished or otherwise formed to increase its
25 stiffness. This may be in the form of a curvature which varies across the diaphragm so that the stiffness is

greater towards the edges of the diaphragm, as shown.
This curvature or profiling of the diaphragm may assist in
scaling the diaphragm while keeping the fc constant, and
may also be beneficial in smoothing the piston to modal
5 transition, especially for larger diaphragms.

In Figure 26 there is shown a circular diaphragm (2)
which is driven by the voice coil of a transducer, not
shown, having a rectilinear coupler (46), equivalent to
the coupler ring (12) of the embodiment of Figures 1 and
10 2, connected between the voice coil and the diaphragm to
provide a straight line drive junction. The coupler (46)
is arranged and disposed on a diameter of the diaphragm
and with its ends equally spaced from the opposite edges
of the diaphragm.

15   In Figure 27 there is shown a rectangular diaphragm
(2) driven by a voice coil of a transducer, not shown,
with a rectilinear coupler (46) connected between the
voice coil and the diaphragm to provide a straight line
drive junction. The coupler (46) is positioned off centre
20 of the diaphragm and angled with respect to the sides of
the diaphragm.

INDUSTRIAL APPLICABILITY

The present invention thus provides an effective way
of increasing the frequency bandwidth of a bending wave
25 speaker.

CLAIMS

1.   A loudspeaker comprising a panel-form acoustic member intended for operation as a bending wave radiator and an electrodynamic moving coil transducer having a voice coil
5 mounted to the acoustic member to excite bending wave vibration in the acoustic member, wherein the junction between the voice coil and the acoustic member is of sufficient length in relation to the size of the acoustic member to represent a line drive such that the acoustic
10 member has a mechanical impedance which has a rising trend with bending wave frequency.

2.   A loudspeaker according to claim 1, wherein the junction between the voice coil and the acoustic member is circular.

15 3.   A loudspeaker according to claim 1 or claim 2, wherein the junction between the voice coil and the acoustic member is substantially continuous.

4.   A loudspeaker according to claim 2 or claim 3, wherein the portion of the acoustic member circumscribed by the
20 said voice coil is of different stiffness to a portion of the acoustic member outside the voice coil.

5.   A loudspeaker according to any preceding claim, wherein the acoustic member is also moved in whole body mode by the transducer.

6.   A loudspeaker according to any one of claims 2 to 5, comprising means mass loading the acoustic member within the diameter of the voice coil.

7.   A loudspeaker according to any preceding claim, 5 wherein the acoustic member is non-circular in shape.

8.   A loudspeaker according to any preceding claim, wherein the transducer voice coil is concentric with the geometric centre of the acoustic member.

9.   A loudspeaker according to any preceding claim, 10 comprising a second transducer coupled to the acoustic member within the portion thereof circumscribed by the said voice coil and adapted to cause high frequency bending wave activity of the said portion.

10.   A loudspeaker according to claim 9, wherein the 15 second transducer is offset from the axis of the said voice coil.

11.   A loudspeaker according to any preceding claim, comprising coupling means attaching the said voice coil to the acoustic member, the coupling means having a footprint 20 of non-circular shape.

12. A loudspeaker according to any preceding claim, wherein the portion of the acoustic member circumscribed by the voice coil is stiffer than a portion of the acoustic member outside the voice coil.

13.   A loudspeaker according to any preceding claim, wherein the bending stiffness of the acoustic member is anisotropic.

14.   A loudspeaker according to any preceding claim,
5 comprising a chassis having a portion surrounding the acoustic member, and a further portion supporting the electrodynamic transducer, and comprising means connected between the acoustic member and the said chassis portion and resiliently suspending the acoustic member on the
10 chassis.

15.   A loudspeaker according to claim 14, wherein the suspension means is connected between the chassis and the margin of the acoustic member.

16.   A loudspeaker according to claim 14 or claim 15,
15 wherein the resilient suspension is adapted to mass load the acoustic member.

17.   A loudspeaker according to any one of claims 14 to 16, wherein the resilient suspension is adapted to damp the acoustic member.

20 18.   A loudspeaker according to any one of claims 14 to 17, wherein the resilient suspension is at least partly formed by a skin of the acoustic radiator.

19.   A loudspeaker according to any preceding claim, wherein the acoustic member has a front side from which
25 acoustic energy is radiated, and comprising acoustic

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masking means positioned over the portion of the acoustic member circumscribed by the said voice coil, the masking means defining an acoustic aperture.

20. A loudspeaker according any preceding claim, wherein the electrodynamic moving coil transducer is offset from the geometric centre of the acoustic member, and comprising a counter balance mass on the acoustic member.

21. A loudspeaker according to any preceding claim, adapted to operate as a full range device.

22. A loudspeaker according to any preceding claim, wherein the acoustic member is dished or otherwise formed to increase its stiffness.

23. A loudspeaker according to any preceding claim, wherein the arrangement is such that the acoustic member is excited in bending wave vibration at frequencies near to or greater than the coincidence frequency.

24. A loudspeaker according to any preceding claim, wherein the size, shape or position of the junction between the voice coil and the acoustic member is arranged in relation to the modal distribution of the acoustic member to achieve a smooth transition from whole body motion at low frequencies to resonant bending wave behaviour at higher frequencies.
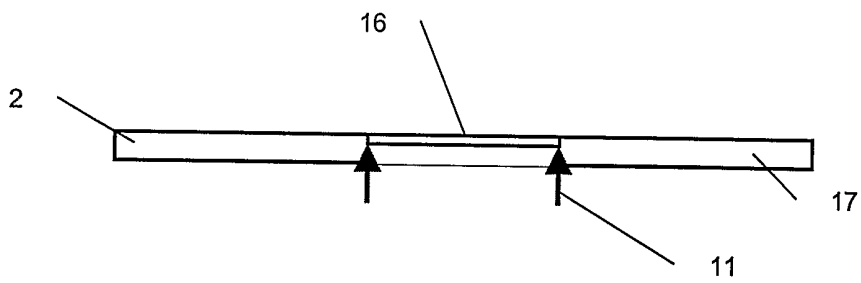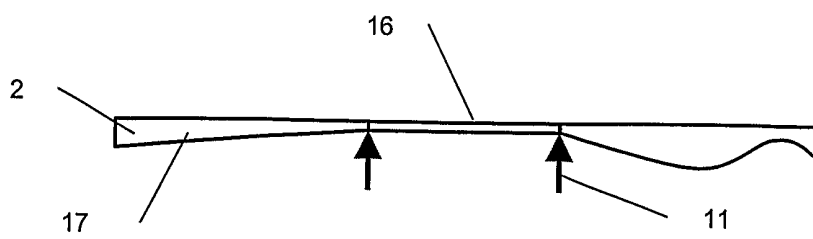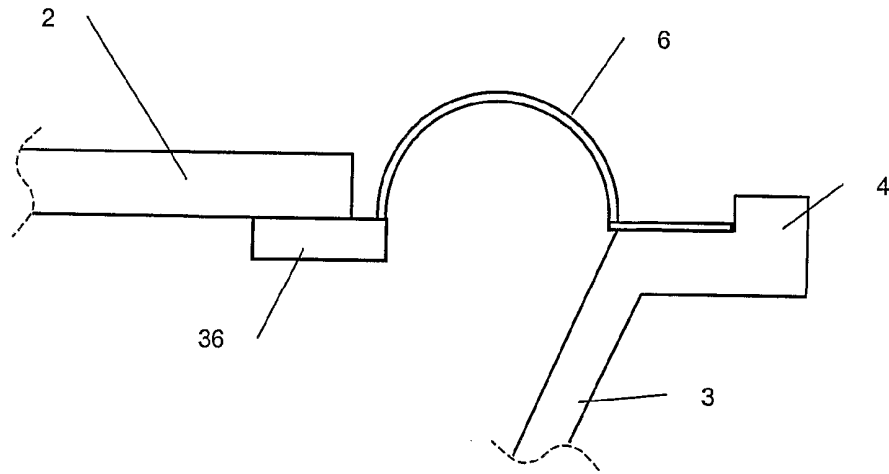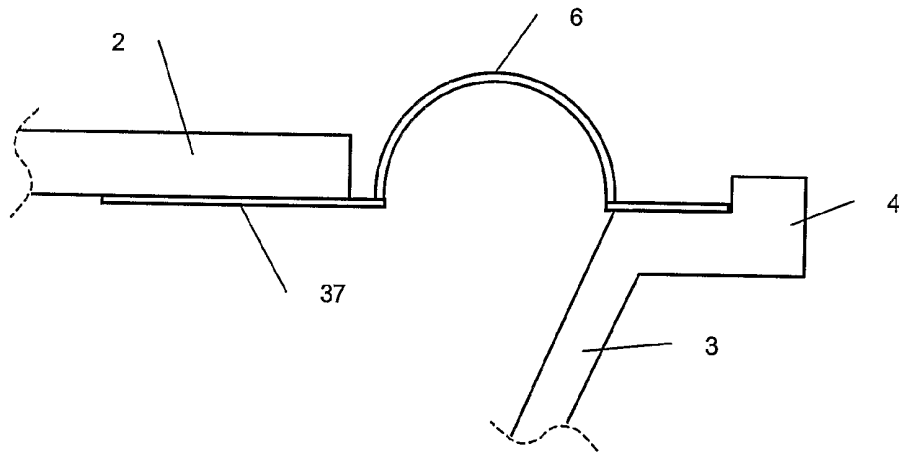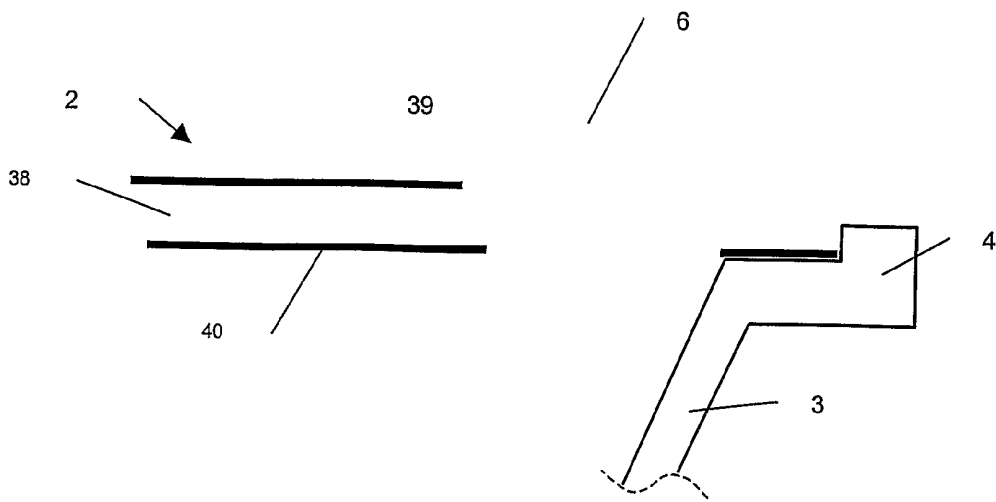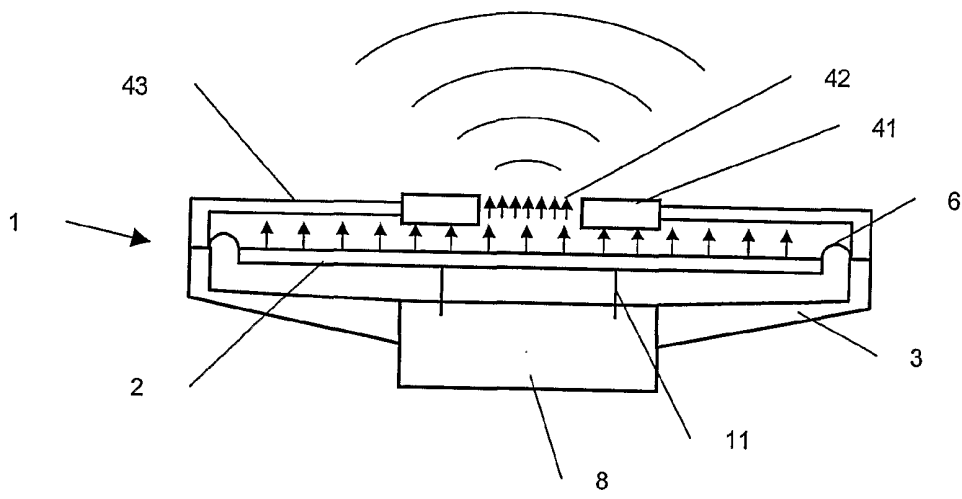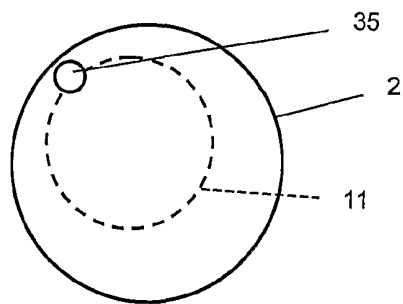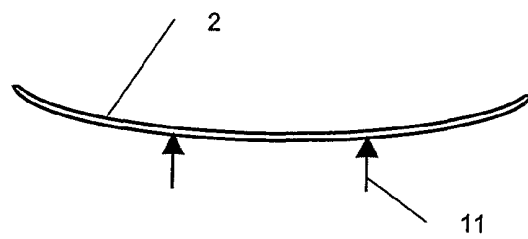
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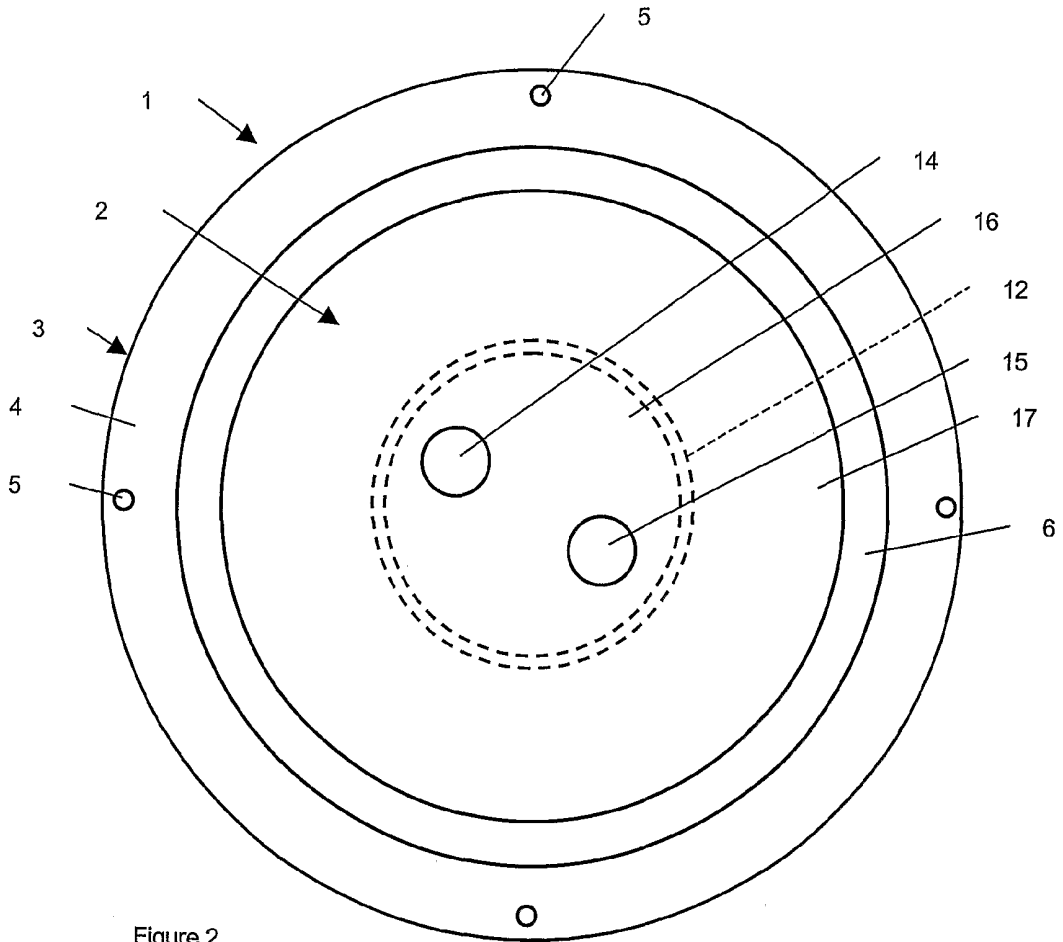
Figure 2

Figure 3

Figure 4

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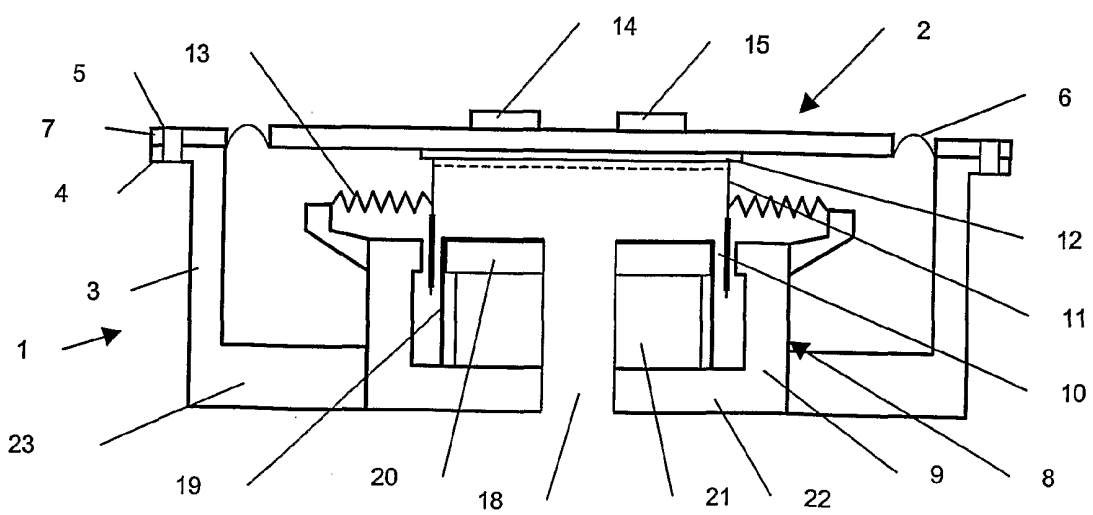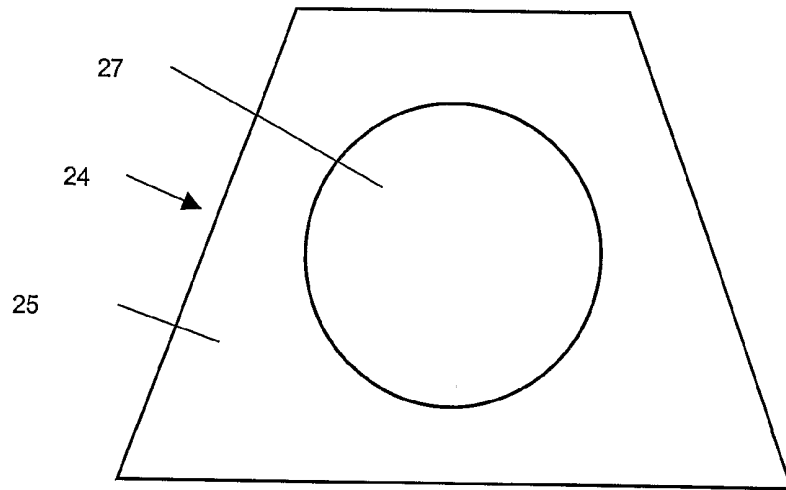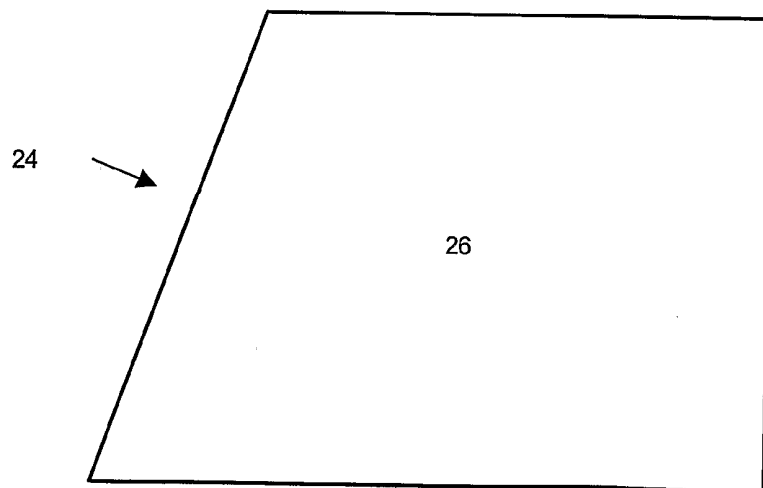
Figure 5

Figure 6

Figure 7
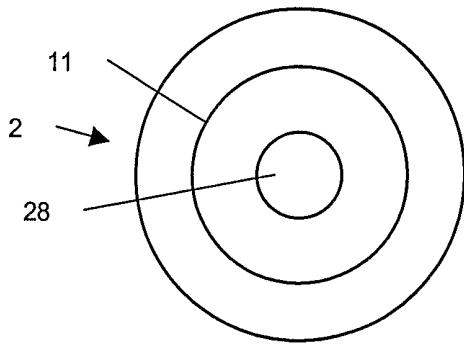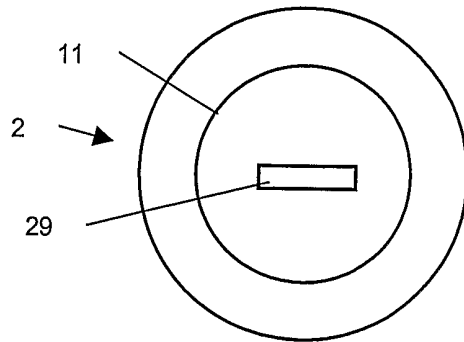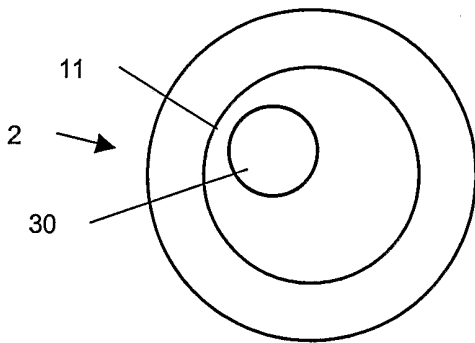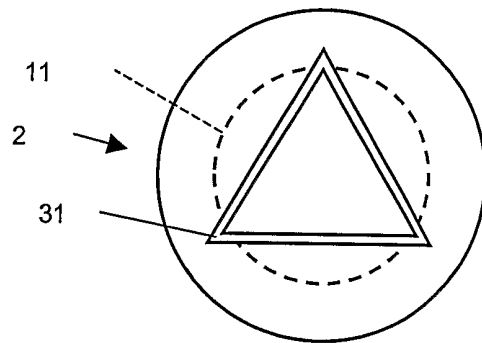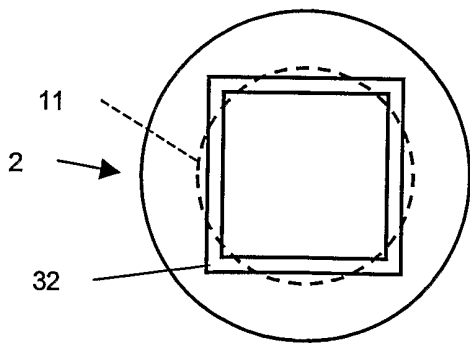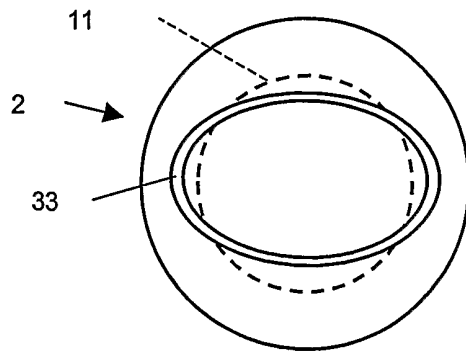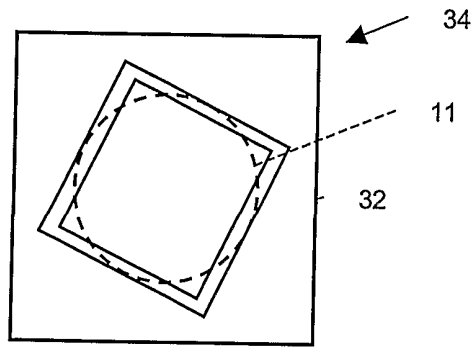
11
2
28

Figure 8

11
2
29

Figure 9

11
2
30

Figure 10

11
2
31

Figure 11

11
2
32

Figure 12

11
2
33

Figure 13

Figure 14

6/9

Figure 15

2

16

11

Figure 16

2

16

11

Figure 17

2

16

17

11

Figure 18

2

16

17

11

Figure 19

2

6

4

36

3

Figure 20

2

6

4

37

3

Figure 21

2   39

6

38

40

4

3
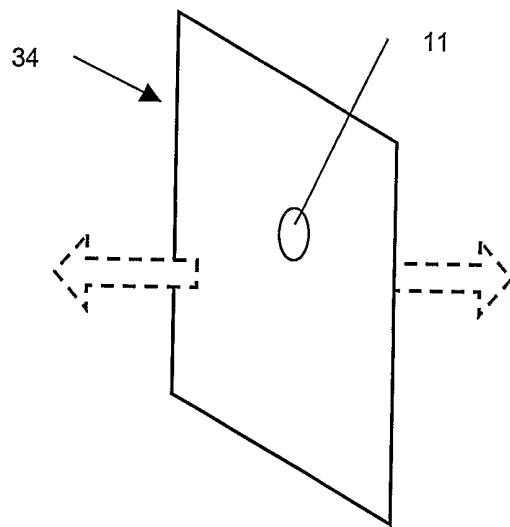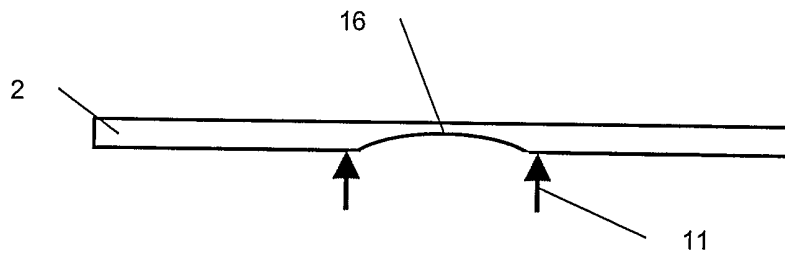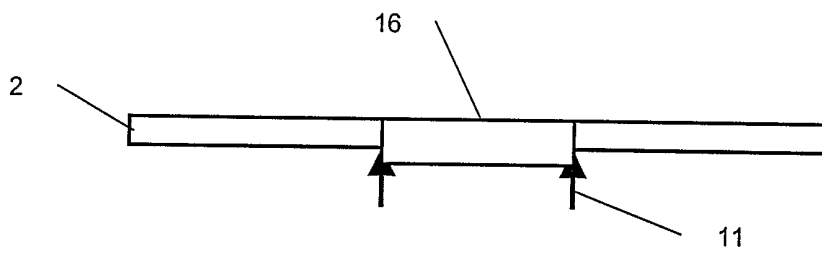
Figure 22

Figure 23

Figure 24

Figure 25

Frequency =18KHz

Figure 26

Figure 27